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# Long-term Variability of the Wind Speed over Land, in Coastal and in Marine Areas



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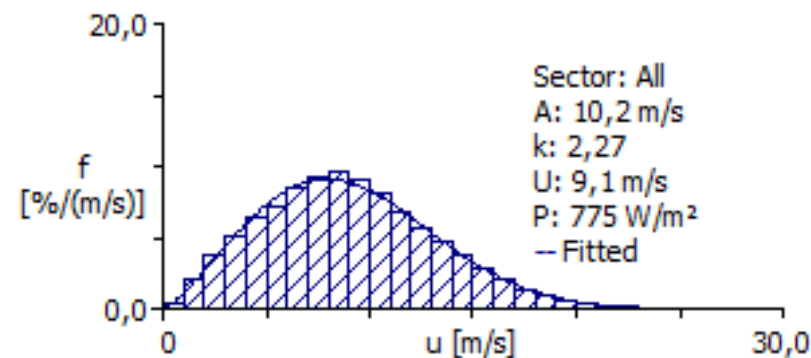
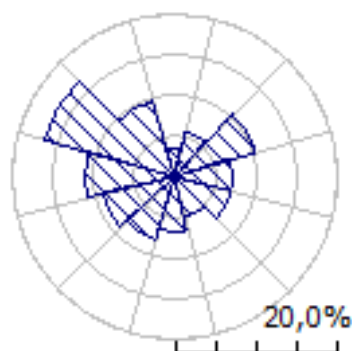
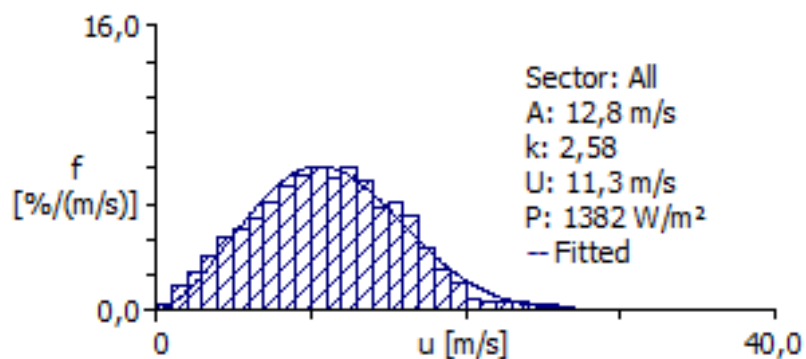
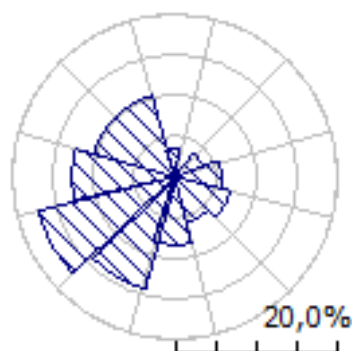
<sup>2</sup>National Institute of Meteorology and Hydrology, Bulgaria



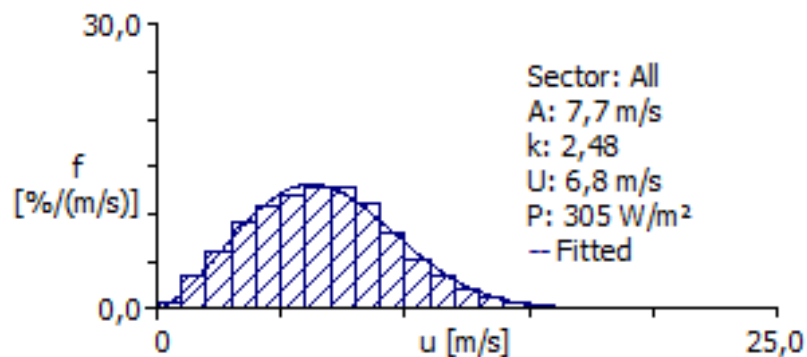
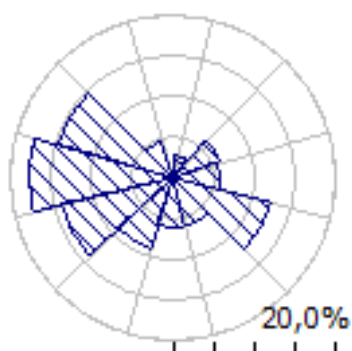
## Outline.

- Lidar Measurements
- Sensitivity to CNR (Carrier to Noise Ratio)
- Profile of Weibull distribution parameters (land, coastal and marine)

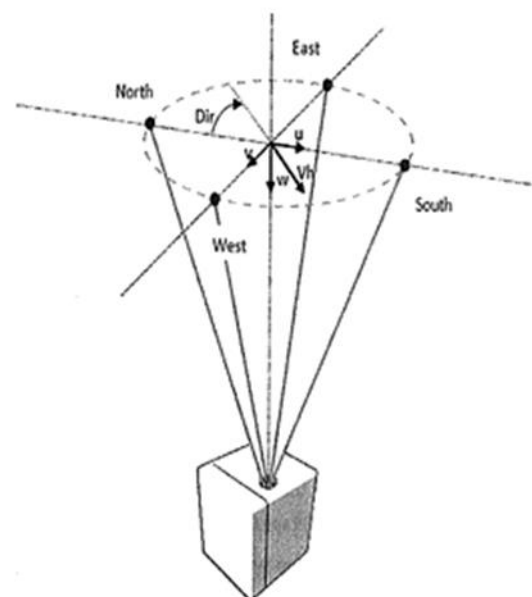
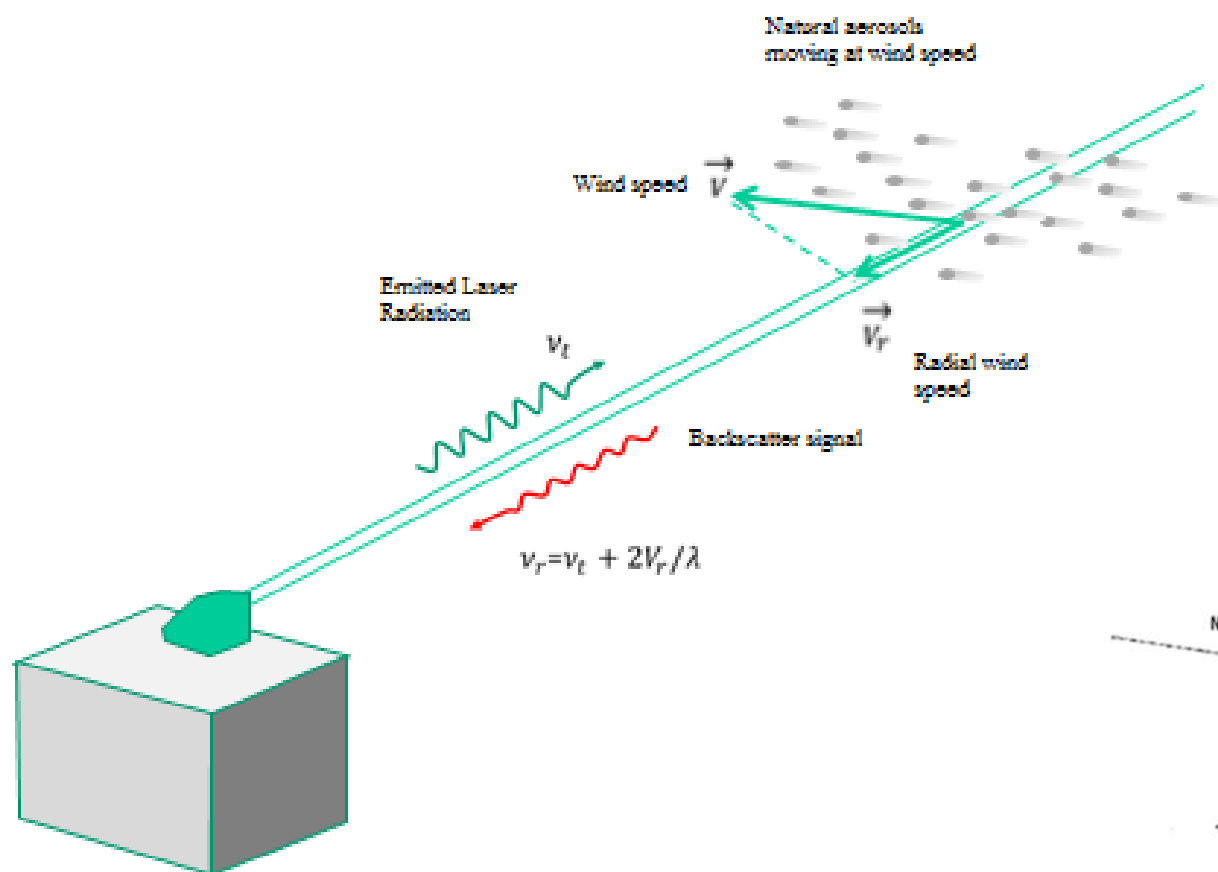
# FINO3



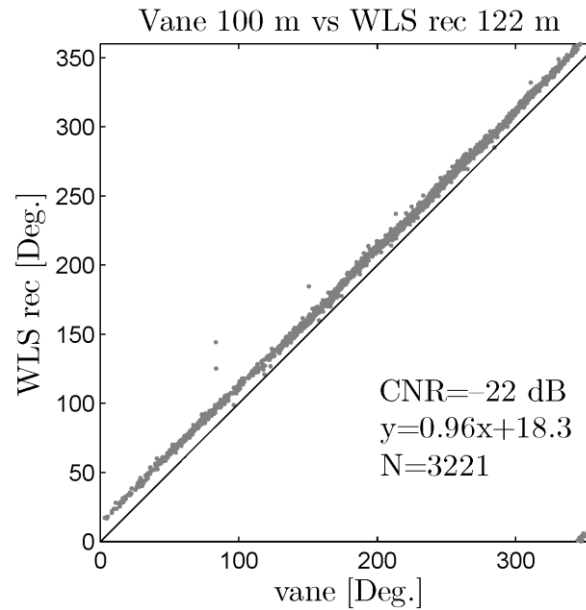
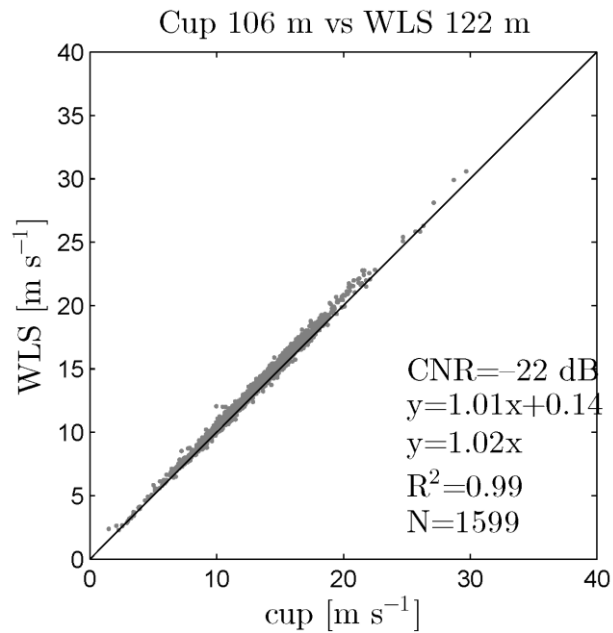
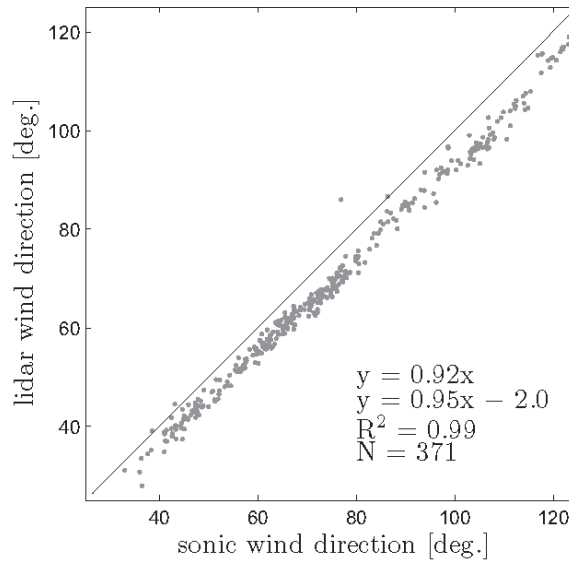
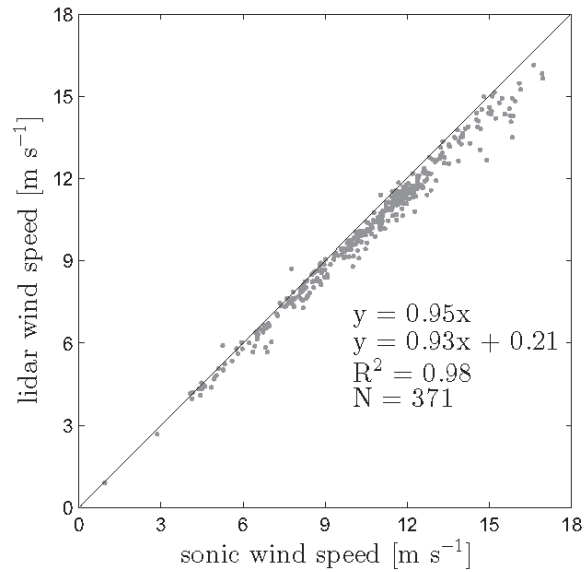
# Coastal



# Hamburg

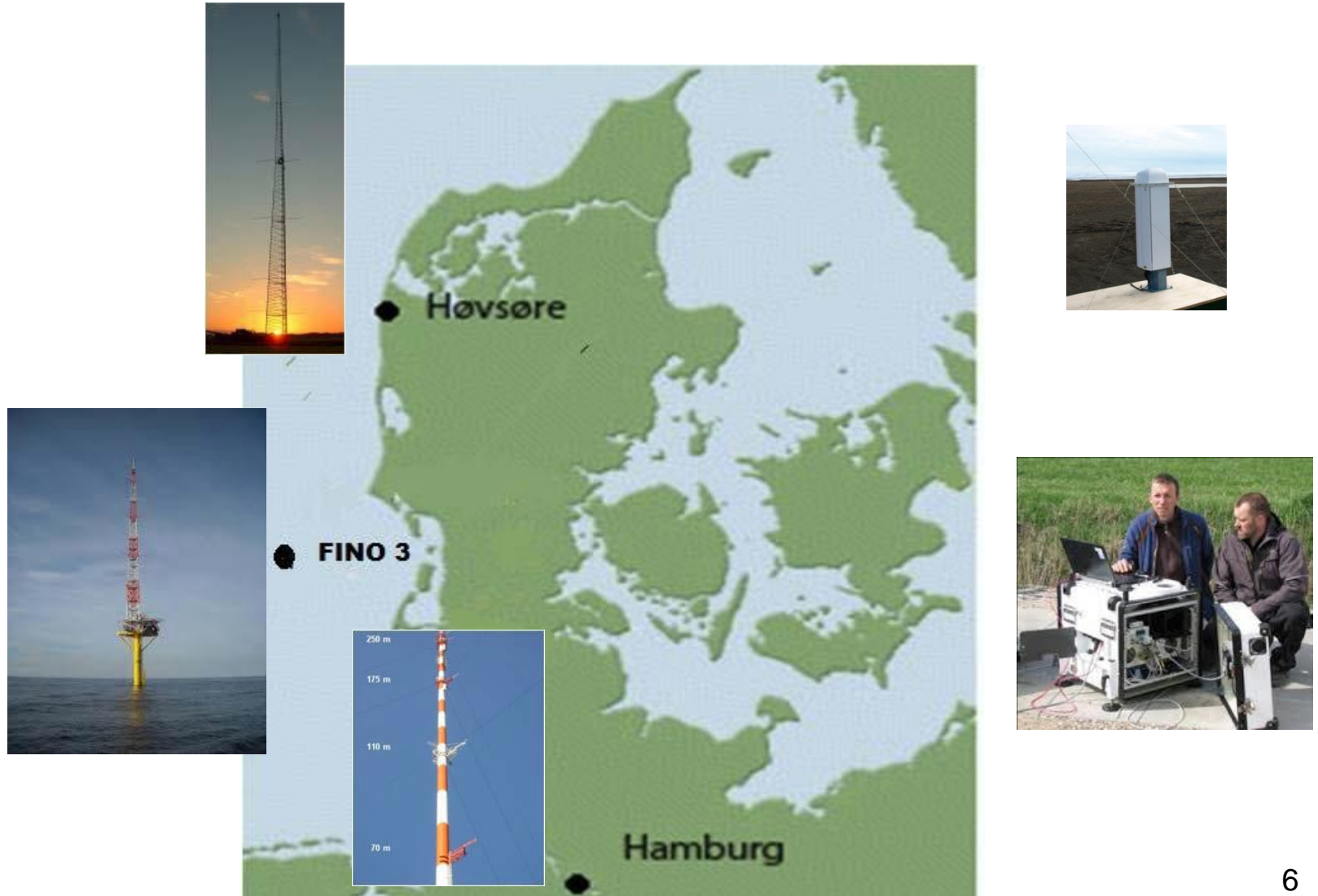


Høvsøre  
coastal



Fino3  
marine

# Tall Wind project







Water



Rural



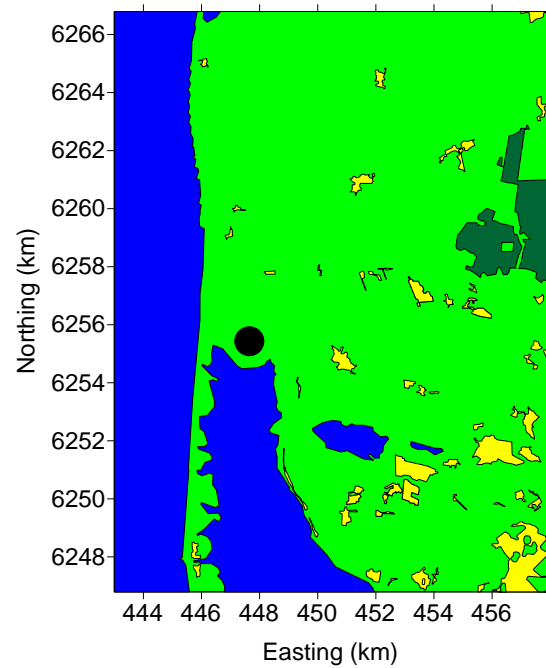
Residential/  
trees /bushes



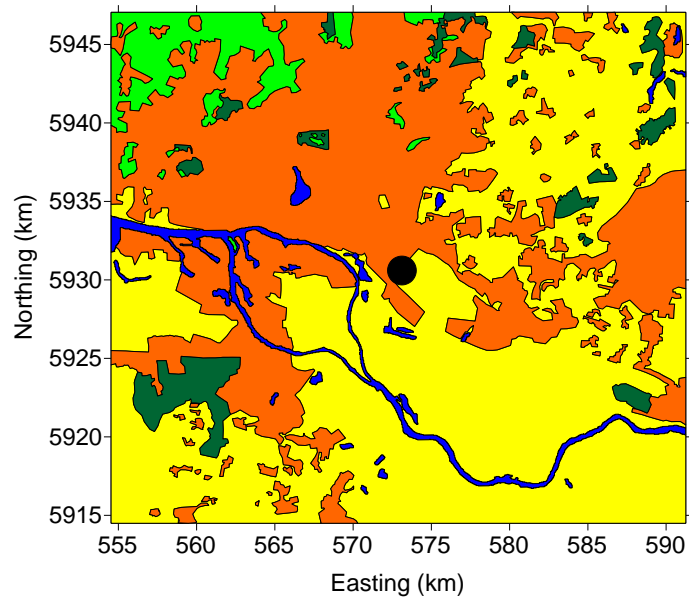
Urban/  
industrial



Forest

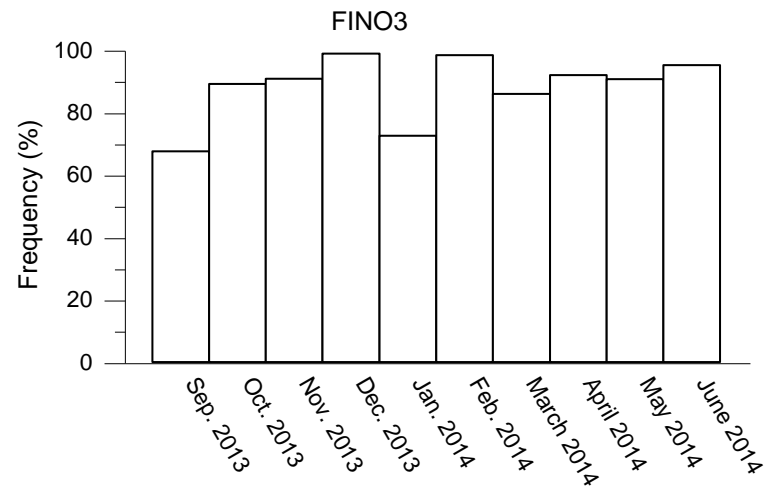
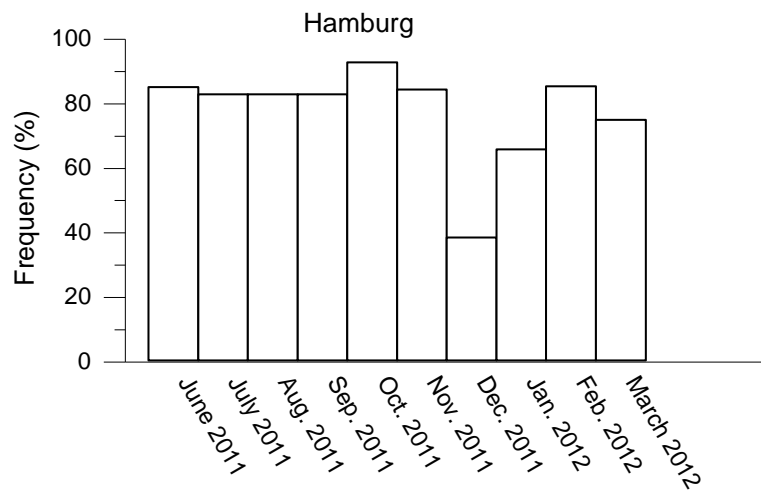
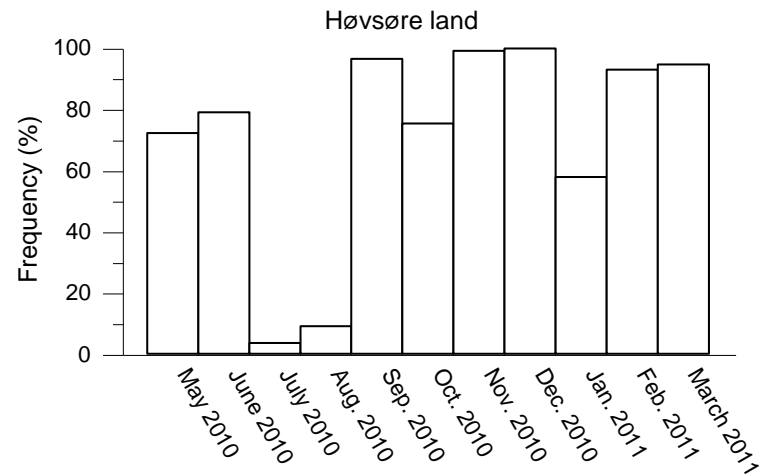
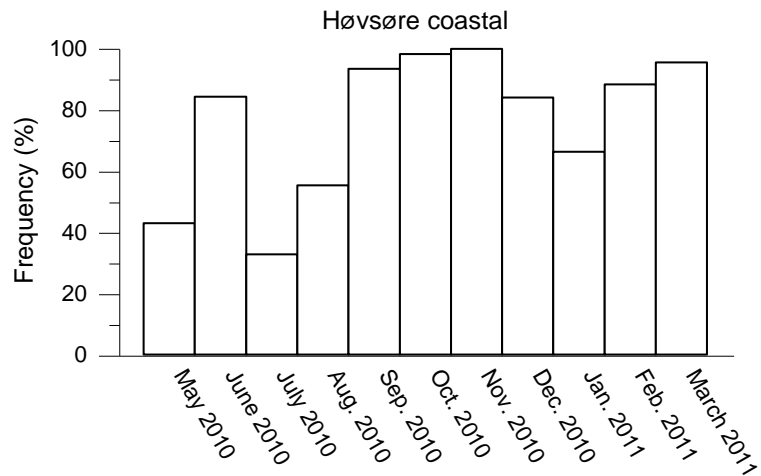


Høvsøre



Hamburg

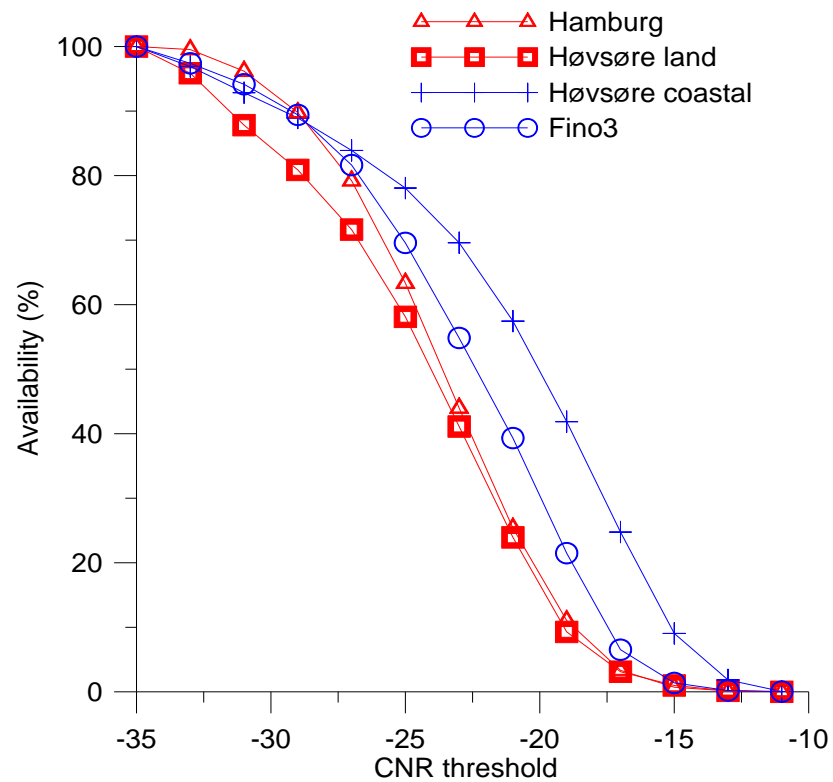




**Table 1** Number of measurements and measuring periods at each site. The numbers in brackets represent the number of wind lidar measurements relative to the total number of cup anemometer measurements.

Site	Wind lidar 100m/600m	Wind lidar and cup anemometer measurements; concurrent and full profiles up to 600 m	Cup anemometer	Period
Høvsøre- land	9885/8876 (84%)/(75%)	8754 (74%)	11758	25 April 2010 – 31 March 2011
Høvsøre- coastal	12618/11616 (73%)/(67%)	11383 (66%)	17377	
Hamburg	34692/27504 (88%)/(70%)	26403 (67%)	39374	15 June 2011 – 23 March 2012
Fino3	40685/34487 (100%)/(85%)	32425 (80%)	40541	29 August 2013– 26 June 2014

# Data availability



# Weibull distribution

$$f(u) = \frac{k}{A} \left(\frac{u}{A}\right)^{k-1} \exp\left(-\left(\frac{u}{A}\right)^k\right)$$

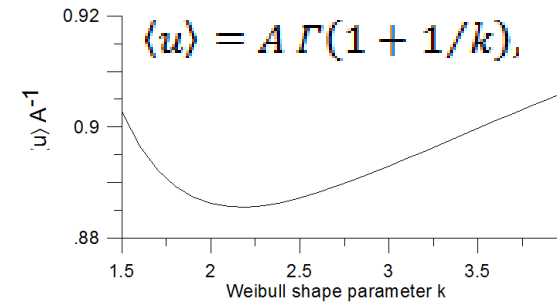
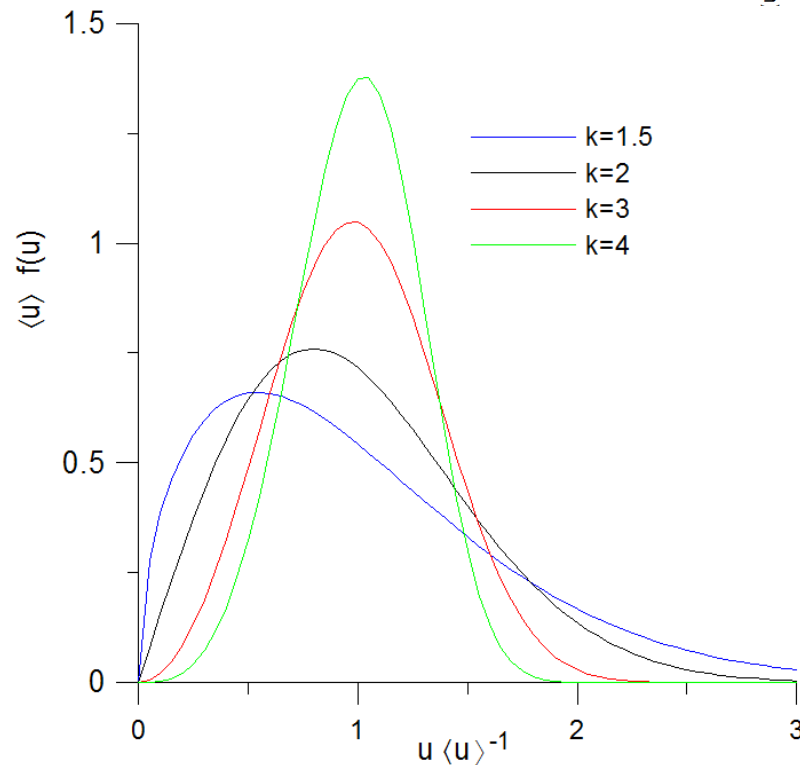
$f(u)$  the probability density function

$u$  Wind speed

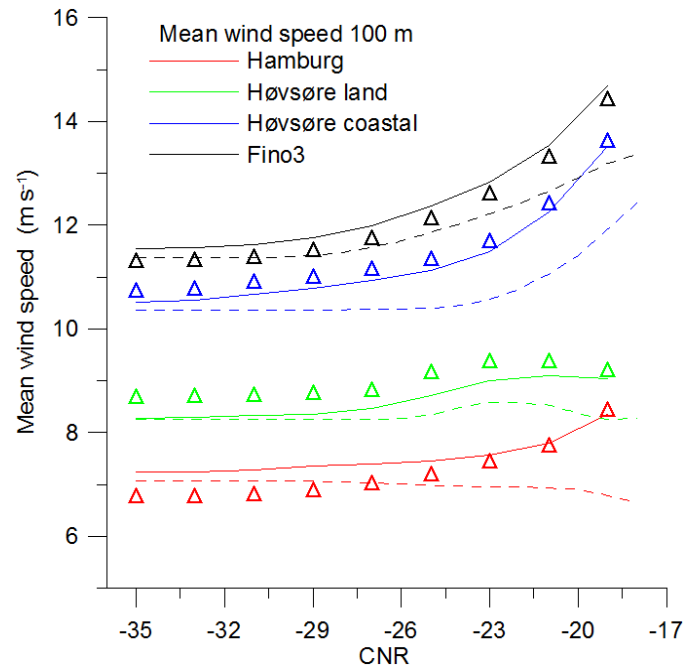
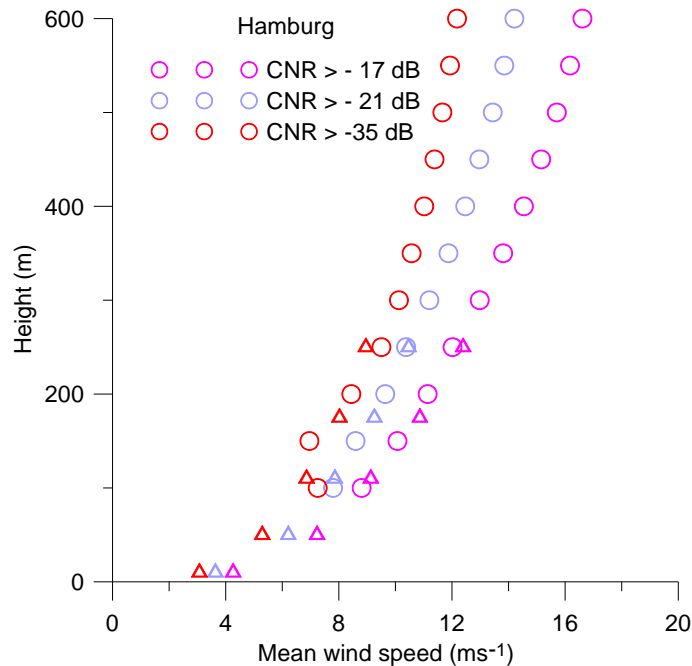
$\langle u \rangle$  Mean wind speed

$A$  Scale factor

$k$  Shape factor



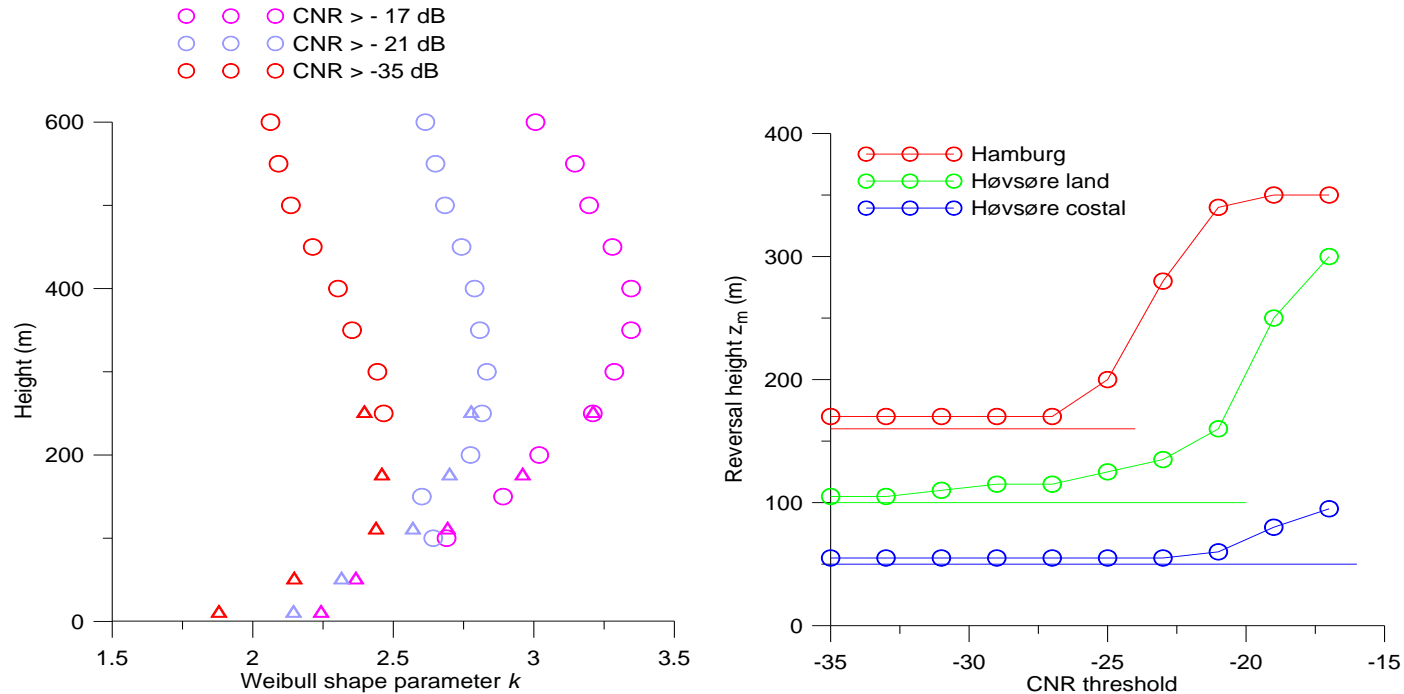
## Mean wind speed - sensitivity to CNR



Left: the wind profile at Hamburg; circles represent observations by the wind lidar and triangles from cup anemometers.

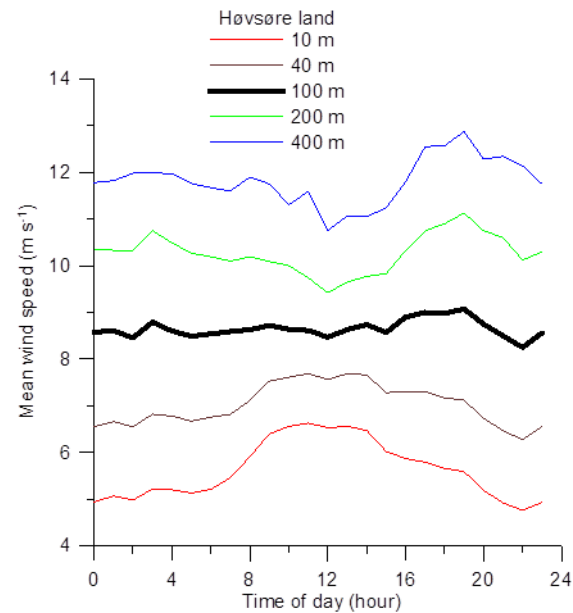
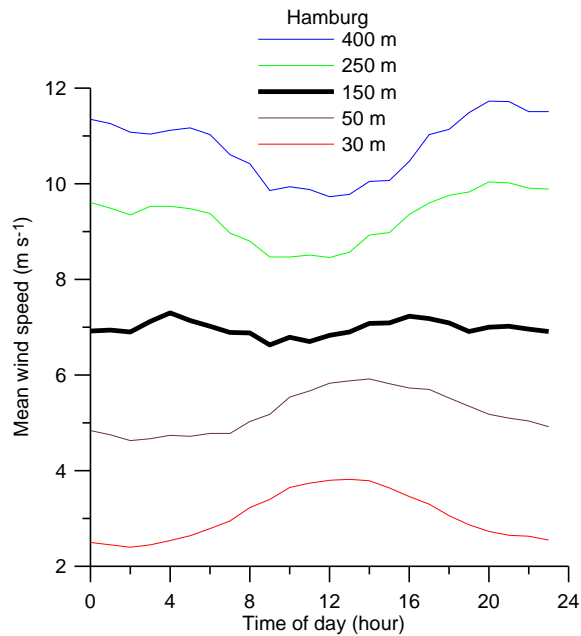
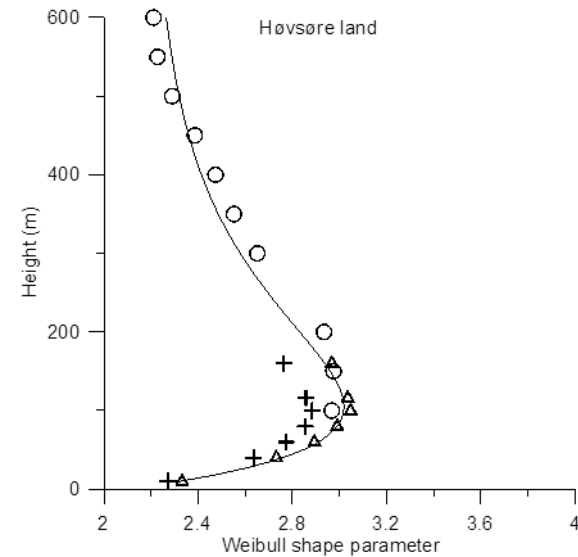
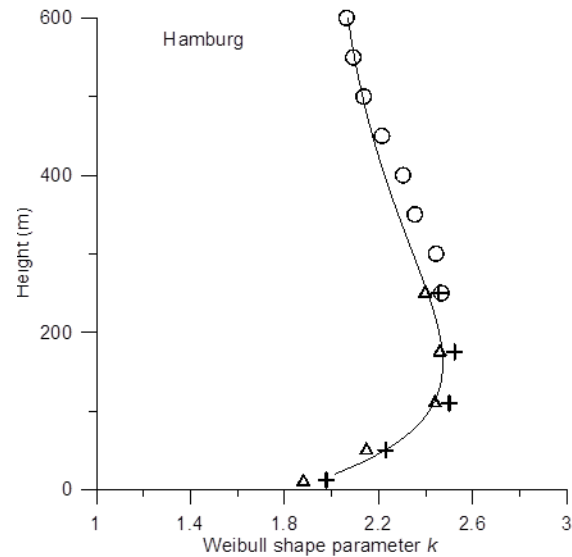
Right: mean wind speed at 100 m as function of the CNR when full profiles up to 600 m are used. The full lines are wind lidar measurements, triangles concurrent wind speed from the cup anemometer. The dashed lines represent the CNR dependency when only the measurements at 100 m are used (no height filter).

## Reversal height – sensitivity to CNR

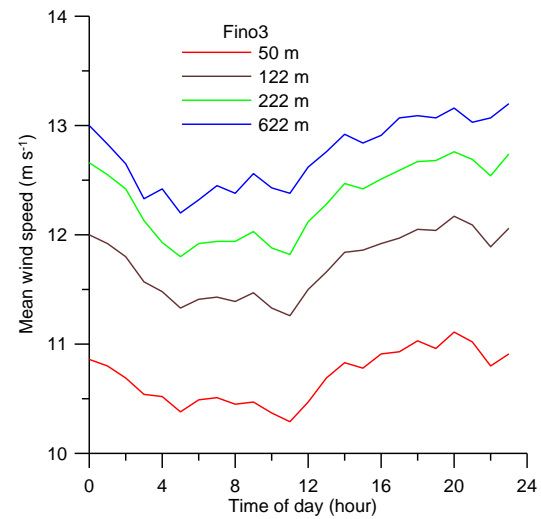
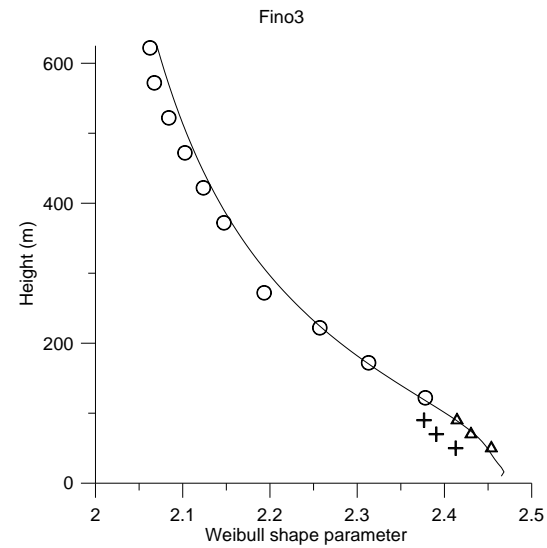
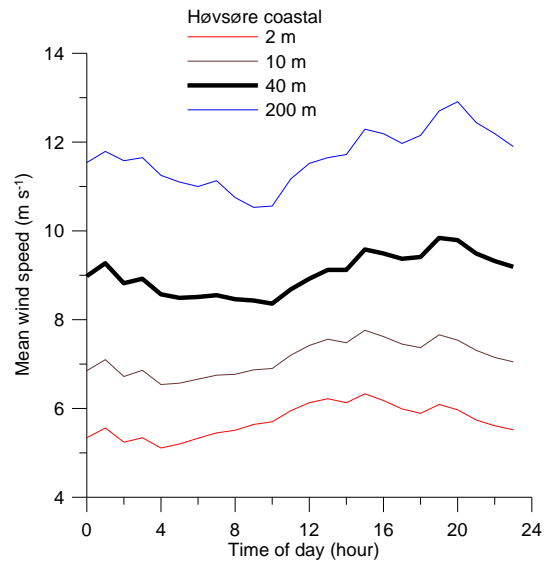
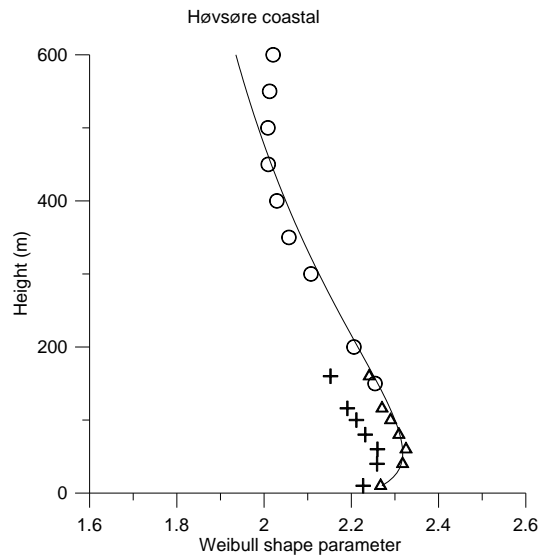


Generally good agreement between mast (triangles) and lidar (circles) for estimates of  $k$ . It is especially visible at Hamburg because of the height of the mast – illustrated here.

# Full line parametrization suggested by Gryning et al. (2014)





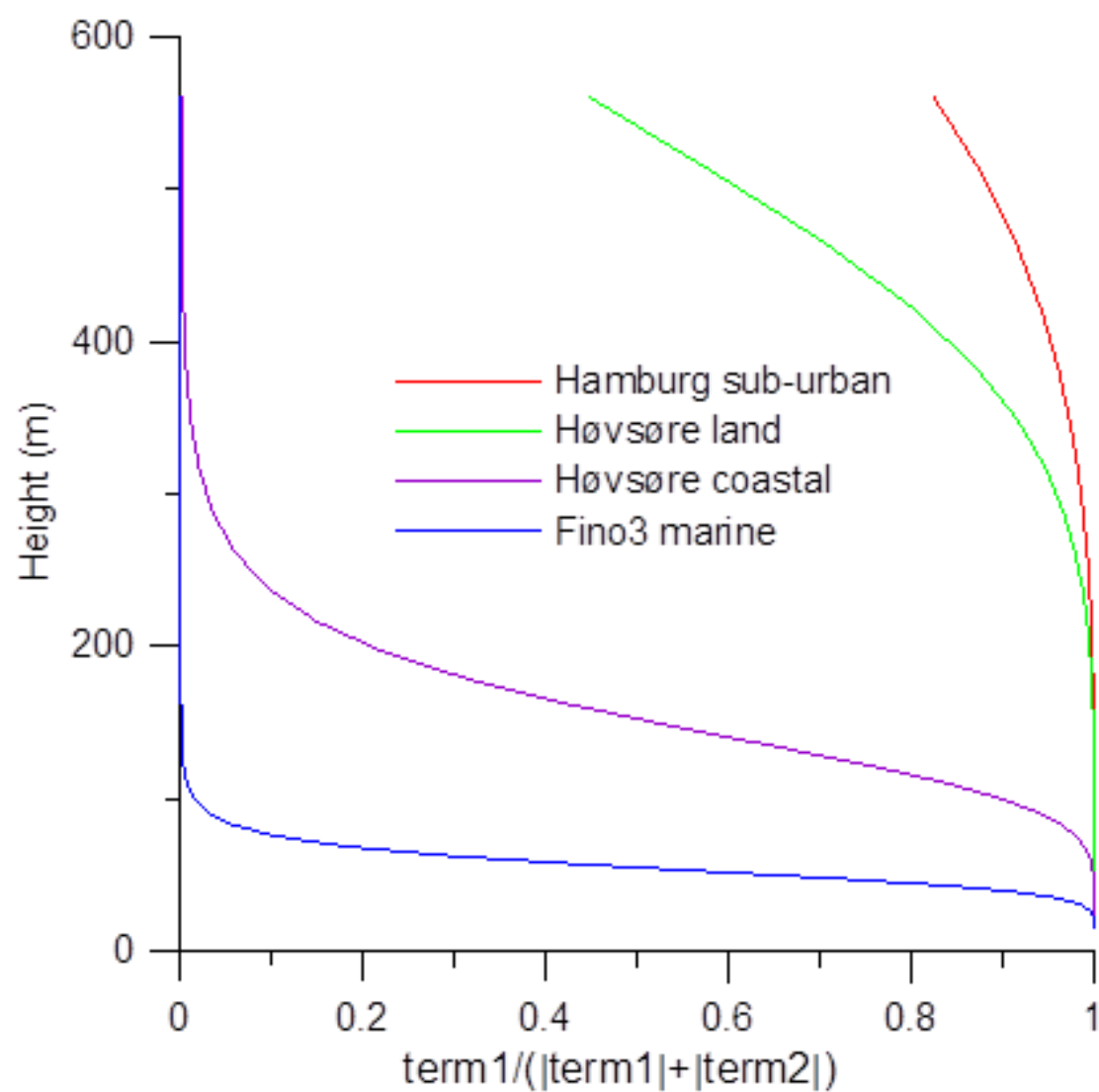


Wieringa (1989): 
$$k = k_s + c_k (z - z_s) \exp \left( -\frac{z - z_s}{z_r - z_s} \right)$$

Gryning et al. (2014)

$$k = k_s + c \frac{z - z_s}{z_r - z_s} \exp \left( -\frac{z - z_s}{z_r - z_s} \right) - (k_s - k_t) \exp \left( -\frac{z_t - z_s}{z - z_s} \right) .$$

where  $k_s$  is the value of the shape parameter at the height  $z_s$  near the ground,  $z_r$  is the height of the shape parameter maximum (reversal height) and  $k_t$  is related to the synoptic value at height  $z_t$ .





Thanks  
for your  
attention